

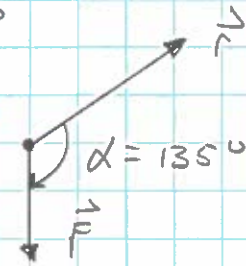
WB 12-6
1

Two ways to do this:

Torque about O :

$$\begin{aligned}\vec{\tau} &= \vec{r} \times \vec{F} \\ |\vec{\tau}| &= rF \sin \alpha \\ &= 50 \text{ Nm}\end{aligned}$$

$$\begin{aligned}F &= 10 \text{ N} \\ r &= \sqrt{5^2 + 5^2} = 7.071 \text{ m}\end{aligned}$$



RHR $\Rightarrow \vec{\tau}$ is into the page which is the $-z$ direction.
So, $\vec{\tau} = -50 \hat{k} \text{ Nm}$

Another way:

$$\vec{\tau} = \vec{r} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5 & 5 & 0 \\ 0 & -10 & 0 \end{vmatrix}$$

$$= \hat{i}(5 \cdot 0 - 0(-10)) - \hat{j}(5 \cdot 0 - 0 \cdot 0) + \hat{k}(5(-10) - 5 \cdot 0)$$

$$\vec{\tau} = -50 \hat{k} \text{ Nm}$$