



at point 0:

$$z_0 = 0$$

$$(x_0, y_0) = (0, 0)$$

$$(v_{x0}, v_{y0}) = (v_0 \cos \theta, v_0 \sin \theta)$$

at point 1:

$$z_1$$

$$(x_1, y_1) = (x_1, h)$$

$$(v_{x1}, v_{y1}) = (v_{x0}, 0)$$

Note: $a_x = 0, a_y = -g$

a.) Find height $h = y_1$

y-motion:

$$v_{y1}^2 = v_{y0}^2 + 2a_y \Delta y \quad \Delta y = y_1 - y_0$$

$$0 = v_0^2 \sin^2 \theta - 2gh$$

$$h = \frac{v_0^2 \sin^2 \theta}{2g}$$

b.) More: How far does it go?

at 2: $(x_2, y_2) = (x_2, 0)$ and t_2

$$(v_{x2}, v_{y2})$$

find $x_2 = \text{"Range"}$

0 → 2: y-motion:

$$y_2 = y_0 + v_{y0} \Delta t + \frac{1}{2} a_y \Delta t^2 \quad \Delta t = t_2 - \frac{t_0}{2}$$

$$0 = v_0 \sin \theta t_2 - \frac{1}{2} g t_2^2$$

$$= t_2 (v_0 \sin \theta - \frac{1}{2} g t_2)$$

$$\text{So: } t_2 = 0 \text{ or } v_0 \sin \theta - \frac{g}{2} t_2 = 0$$

$$\text{So } t_2 = \frac{2 v_0 \sin \theta}{g}$$

Now, x-motion:

$$x_2 = x_0 + v_{x0} \Delta t + \frac{1}{2} a_x \Delta t^2 \quad \Delta t = t_2 - \frac{t_0}{2}$$

$$= v_0 \cos \theta t_2$$

So

$$x_2 = v_0 \cos \theta \left(\frac{2 v_0 \sin \theta}{g} \right)$$

$$= \frac{2 v_0^2 \sin \theta \cos \theta}{g}$$

Or, use the trig. identity:

$$\sin(2\theta) = 2 \sin \theta \cos \theta$$

So:

$$R = x_2 = \text{Range} = \frac{v_0^2 \sin(2\theta)}{g}$$

"Range Equation"

c.) The range will be maximum when

$$\theta = 45^\circ \text{ since } \sin(2 \cdot 45^\circ) = 1.$$